

Microblaze Linux

Using an FPGA-based processor is:

Very intelligent

Very stupid

Don't know

Microblaze Linux

Using an FPGA-based processor is:

- Very intelligent ✓
- Very stupid ✓
- Don't know □

Leibniz: *The current world is the best one possible*
... Let's improve it

Contents

- **Intro + motivation**
- **Minimal target hardware**
- **Prerequisites**
- **EDK design**
- **Running the system**
- **To Do's**

Why?

- **Processing power typically not an issue ...**
- **Test software**
- **Communication**
- **μC replacement**

Why Linux?

- **Linux widespread on standard server and desktop PC**
 - ⇒ Many developers familiar with tools and system
 - ⇒ Robust system
 - ⇒ Various distributions (Ubuntu, RedHat, SUSE, ...)
- **Opensource kernel and tools**
 - ⇒ Already ported to many architectures
 - Standard kernel supports Microblaze (since 2.6.36.2)
 - ⇒ Busybox toolset (*swiss-army knife of embedded systems*)
- **Customisable (e.g. no graphics and disk) for small footprint**
 - ⇒ Special version (uClinux) for non-MMU systems
 - ⇒ **We use the standard MMU kernel**
- **Loadable drivers (kernel modules)**
- **Built-in multi-threading, multi-processing**
 - ⇒ Preemptive kernel (optional)
 - ⇒ Multiple task priorities
- **Networking**
 - ⇒ Simplifies development process (multiple terminals, ftp)
 - ⇒ Time, WWW, mail, ...

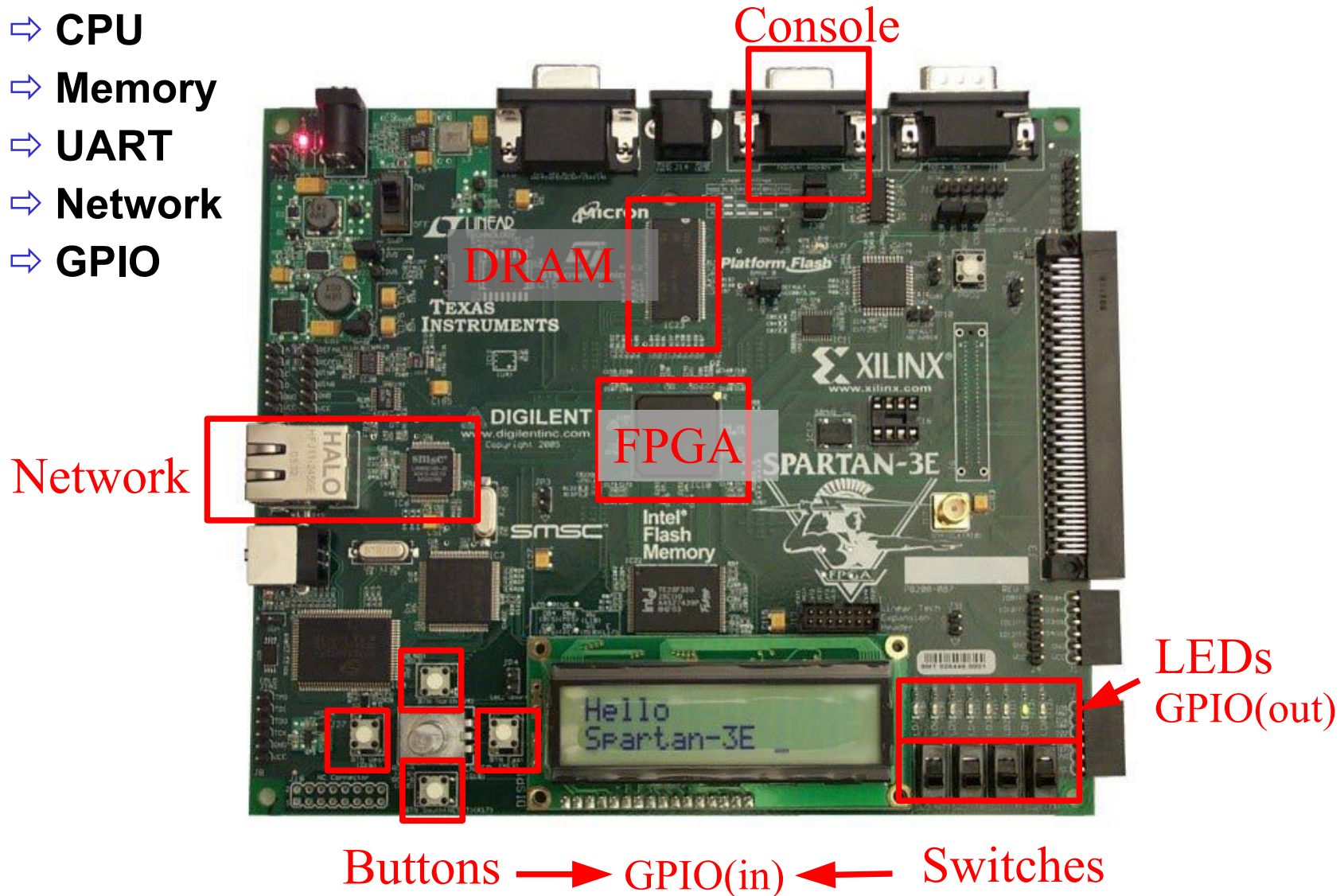
Target HW

- **All modern FPGAs can host a processor**
 - ⇒ **Openrisc etc**
 - ⇒ **Nios (Altera), Microblaze (Xilinx)**
 - ⇒ **Hard-IP: Arm (Altera), PowerPC (Xilinx)**
- **Minimal FPGA design (Mblaze, DRAM, RS232, Network, GPIO)**
 - ⇒ **Spartan3, Spartan6, Virtex4, Virtex5, Virtex6**
 - ⇒ **Mblaze speed 50 .. 125MHz**
 - ⇒ **32MB DRAM minimum?**
 - ⇒ **Access to custom hardware (= FPGA fabric) via GPIO, EPC, FSL possible.**

Test case: Linux on XILINX starter kit

○ Elements

- ⇒ CPU
- ⇒ Memory
- ⇒ UART
- ⇒ Network
- ⇒ GPIO



Prerequisites (1)

○ Hardware platform

⇒ Define in EDK

⇒ Minimal set of elements for reasonable system

- Microblaze CPU with MMU and cache
- DRAM memory (64MB)
- Linux console (Uart lite with IRQ)
- Dual timer (with IRQ)
- Network (ethernet lite with IRQ)
- GPIO for LEDs
- GPIO for buttons and switches
- Interrupt controller
- Debug module (MDM)

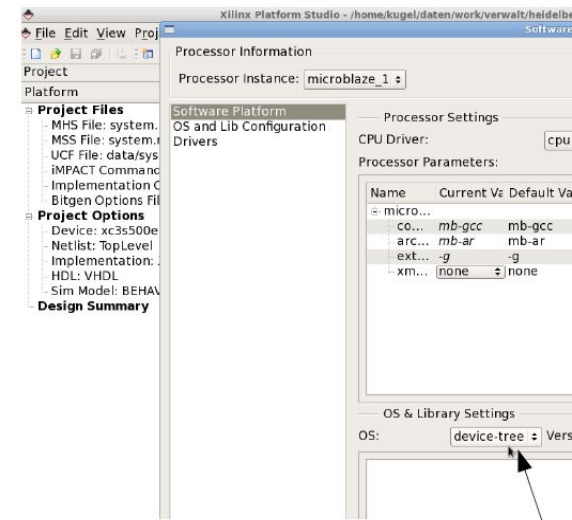
⇒ Set DRAM base address to 0xc0000000

⇒ Select „device-tree“ in SW platform

⇒ Generate addresses

⇒ Compile libraries

- *Don't select any app for BRAM init*
- Produces device tree directory



Prerequisites (2)

○ Xilinx tools

⇒ Install ISE and EDK

⇒ Gcc (mb-gcc) to compile kernel comes with EDK

⇒ Toolset for Linux applications from Xilinx GIT server

- http://git.xilinx.com/?p=mb_gnu.git;a=summary

- Microblaze-unknown-linux-gnu-gcc (etc.)

- Sample ram disk images

- System include files and libraries for Linux

⇒ Device-tree-generator for EDK from Xilinx GIT server

- <http://git.xilinx.com/?p=device-tree.git;a=summary>

- „bsp“ directory must be copied to root of EDK project

○ Many useful Xilinx infos

⇒ <http://xilinx.wikidot.com>

⇒ Xilinx-version of Linux kernel available

- Few more drivers and configurations

- Less portable

Prerequisites (3)

○ Download Linux application(s): Busybox

⇒ <http://busybox.net/> (current version 1.18.1)

⇒ Busybox contains almost all basic Linux programs in a single binary (some with limited functionality)

○ Configure Busybox

⇒ Copy arch/i386 to arch/microblaze

⇒ Edit arch/microblaze/Makefile

- Add to CFLAGS: `-L . -L mbtooldir/microblaze_v1.0/microblaze-unknown-linux-gnu/microblaze-unknown-linux-gnu/sys-root/usr/lib --sysroot=linuxrootdir -isystem mbtooldir/microblaze_v1.0/microblaze-unknown-linux-gnu/microblaze-unknown-linux-gnu/sys-root/usr/include`

⇒ Add path to Linux GCC

- `export PATH=$PATH:mbtooldir/microblaze_v1.0/microblaze-unknown-linux-gnu/bin`

⇒ Copy `mbtooldir/microblaze_v1.0/microblaze-unknown-linux-gnu/microblaze-unknown-linux-gnu/sys-root/usr/lib/crt*.o` to `.`

⇒ Make `ARCH=microblaze CROSS_COMPILE=microblaze-unknown-linux-gnu-` ; make install

- Directory structure with busybox binary and soft links in `_install/`

- Busybox files

- Init
- bin:
○ [cryptpw fgrep length od seq traceroute [[cttyhack find less openvt setarch true
addgroup cut fold linux32 passwd setkeycodes tty adduser date free linux64 patch setsid
tysize ar dc ftpget ln pgrep setuidgid udpsvd arping dd ftpput logger pidof sh
umount ash dealloctv fuser login ping sha1sum uname awk delgroup getopt logname
ping6 showkey uncompress basename deluser grep lpq pipe_progress sleep unexpand
busybox dirname hd lsattr printf split unlzma bzip2 diff gzip ls printenv sort unix2dos
bzip2 dos2unix hexdump makemime pscan strings uptime cal dpkg hostid md5sum pwd
stty usleep cat dpkg-deb hostname mesg readlink su uudecode catv du id microcom
realpath sum uuencode chat dumpkmap install mkdir reformmime sv vi chatr dumpleases
ip mkfifo renice sync vlock chgrp echo ipaddr mknod reset tac watch chmod ed ipcalc
mktemp resize tail wc chown egrep ipcrm more rm tar wget chpst eject ipcs mount rmdir
tcpsvd which chrt env iplink mountpoint rpm tee who chvt envdir iproute mt rpm2cpio
telnet whoami cksum envuidgid iprule mv rtcwake test xargs clear ether-wake iptunnel nc
run-parts tftp yes cmp expand kbd_mode netstat runsv tftpd zcat comm expr kill nice
runsvdir time cp false killall nmeter rx top cpio fdflush killall5 nohup script touch
crontab fdformat last nslookup sed tr
- sbin:
○ adjtimex dnssd hdparm loadfont nameif runlevel swapon arp fakeidentd httpd loadkmap
pivot_root sendmail switch_root blkid fbset hwclock logread popmaildir setconsole sysctl
brctl fbsplash ifconfig losetup poweroff setfont syslogd chpasswd findfs ifdown lpd
raidautorun setlogcons telnetd chroot freeramdisk ifenslave makedevs rdate slattach
udhcpc crond fsck ifup man rdev start-stop-daemon udhcpd devfsd fsck.minix inetd mdev
readprofile sulogin vconfig devmem getty init mkfs.minix reboot svlogd watchdog
dhcprelay halt klogd mkswap route swapoff zcip

Prerequisites (4)

- Create directory for initial ram disk, e.g. /tmp/ramdisk
- Extract template
 - ⇒ cd /tmp/
 - ⇒ gzip -d -c *mbtooldir/microblaze_v1.0/initramfs_minimal.cpio.gz* > ramfs.cpio
 - ⇒ cd ramdisk
 - ⇒ sudo cpio -i < ../ramfs.cpio
 - > ls
 - bin dev etc **init** mnt proc sbin sys tmp var
 - >
- Replace template binaries with new Busybox
 - ⇒ sudo rm -rf bin sbin
 - ⇒ sudo cp -r *busyboxdir/_install/** .
- Set root owner of new binaries
 - ⇒ sudo chown -R 0.0 init bin sbin
- Add user files, etc to /lib/modules, /src, /var/www
- Edit startup script /etc/init.d/rcS
 - ⇒ Next slide

- Startup script /etc/init.d/rcS

```
#!/bin/sh
/bin/echo "Starting rcS"
/bin/echo "++ Creating device points"
/bin/mkdir /dev/pts
/bin/mount -t devpts devpts /dev/pts
/bin/echo "++ Mounting filesystem"
/bin/mount -t proc none /proc
/bin/mount -t sysfs none /sys
/bin/echo "++ Loading system loggers"
/sbin/syslogd
/sbin/klogd
/bin/echo "++ Starting telnet daemon"
/sbin/telnetd -l /bin/sh
/bin/echo "++ Starting network at 192.168.0.10"
/sbin/ifconfig eth0 192.168.0.10 up
/bin/echo "++ Starting HTTPD"
/sbin/httpd -h /var/www
/bin/echo "++ Creating user ftp"
/bin/cat /dev/null >> /etc/passwd
/bin/cat /dev/null >> /etc/group
/bin/adduser -D -H -h /tmp ftp
/bin/echo "++ Starting INETD (e.g.for ftp)"
/sbin/inetd -e /etc/inetd/inetd.conf
/sbin/route add 192.53.103.108 gw 192.168.0.1 eth0
/sbin/rdate 192.53.103.108
/bin/echo "rcS Complete"
```

Prerequisites (5)

○ Download Linux kernel

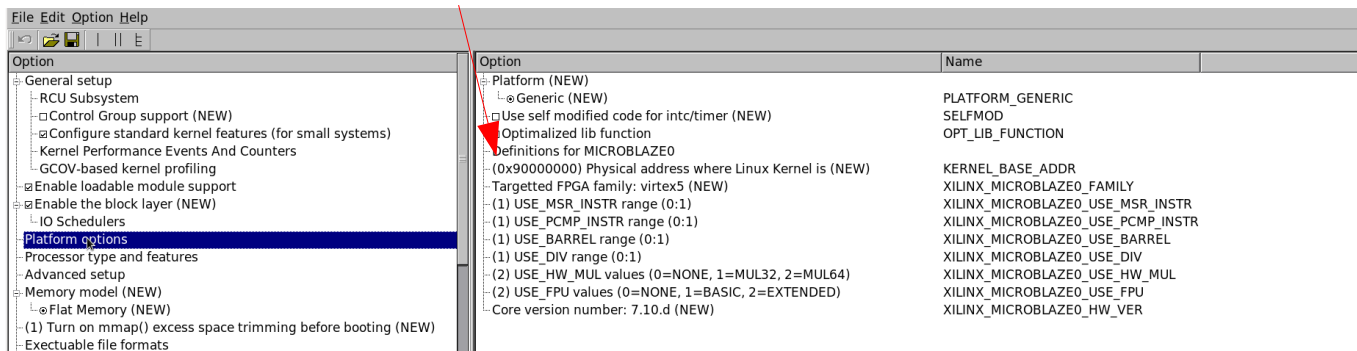
⇒ <http://www.kernel.org/pub/linux/kernel/v2.6/linux-2.6.38.2.tar.bz2>

○ Configure kernel

⇒ Copy arch/microblaze/configs/mmu_defconfig to .config

⇒ Make ARCH=microblaze CROSS_COMPILE=mb- xconfig

- Shows configuration options
- Set /tmp/ramfs as directory for initial ram disk
- Set memory to 0xc000000 (problem with current linker script)



Check .config after saving against tutorial .config to see all differences

⇒ Copy device tree from EDK microblaze0/libsrc/device-tree/xilinx.dts to arch/microblaze/boot/dts

⇒ Make ARCH=microblaze CROSS_COMPILE=mb- simpleImage.xilinx

- Kernel binary in arch/microblaze/boot/simpleImage.xilinx

Prerequisites (6)

- **More on kernel configuration**
 - ⇒ **MMU enabled**
 - ⇒ **XILINX uartlite (+ console), ethernetlite, GPIO enabled**
 - ⇒ **Preemptive kernel enabled**
 - ⇒ **Microblaze options and versions must match EDK**
 - **MMU: 3**
 - **Barrel shifter: 1, HW mult: 1 (32 bit), MSR: 1, PatCmp: 1**
 - **Divider: 0, Float: 0**
 - ⇒ **DRAM address can be set in config dialog but seems to be ignored in linker script => use 0xc0000000**
 - ⇒ **GPIO enabled**

Prerequisites (7)

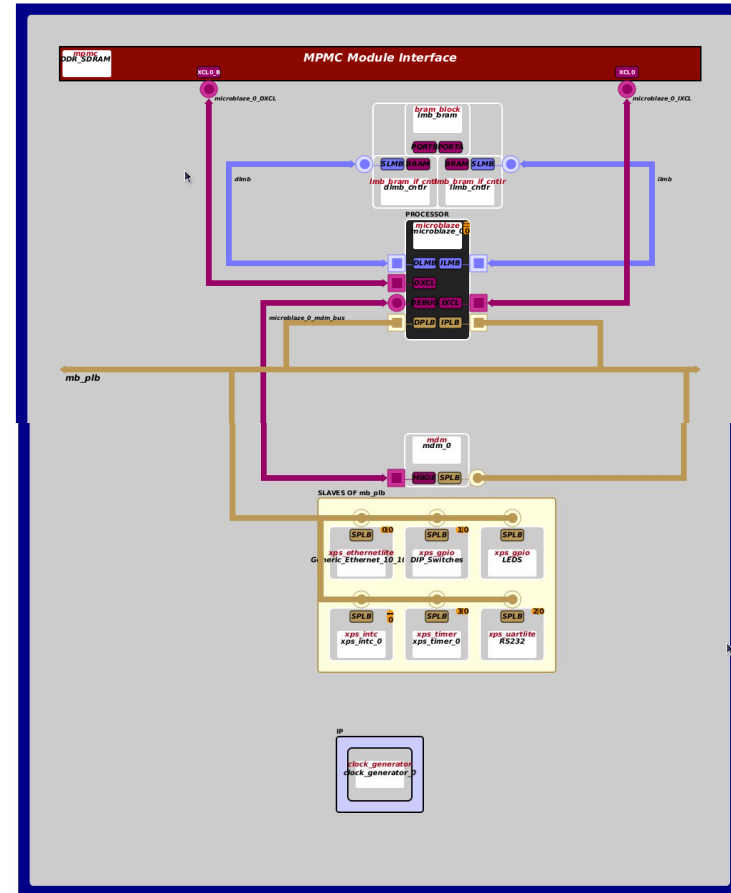
○ Kernel compilation result

- ⇒ ...
- ⇒ **SYSMAP** System.map
- ⇒ **SYSMAP** .tmp_System.map
- ⇒ **CP** vmlinux
arch/microblaze/boot/simpleImage.xilinx_sp3.unstrip
- ⇒ **OBJCOPY** arch/microblaze/boot/simpleImage.xilinx_sp3
- ⇒ **UIMAGE** arch/microblaze/boot/simpleImage.xilinx_sp3.ub
- ⇒ **Image Name:** Linux-2.6.36.2
- ⇒ **Created:** Sun Jan 9 18:29:22 2011
- ⇒ **Image Type:** MicroBlaze Linux Kernel Image (uncompressed)
- ⇒ **Data Size:** 5172900 Bytes = 5051.66 kB = 4.93 MB
- ⇒ **Load Address:** c0000000
- ⇒ **Entry Point:** c0000000
- ⇒ **STRIP** arch/microblaze/boot/simpleImage.xilinx_sp3
- ⇒ **Kernel:** arch/microblaze/boot/simpleImage.xilinx_sp3 is ready (#31)
- ⇒ [kugel@akudesk linux-2.6.36.2]\$

Creating the HW

Bus Interfaces Ports Addresses Clean All Generated

| Name | Bus | IP Type | IP Versio |
|---------------------------|-----|---------------|-----------|
| dmb | | ★ lmb_v10 | 1.00.a |
| ilmb | | ★ lmb_v10 | 1.00.a |
| mb_plb | | ★ plb_v46 | 1.05.a |
| + microblaze_0 | | ★ microblaze | 8.00.b |
| + lmb_bram | | ★ bram_bl... | 1.00.a |
| + dmb_cntlr | | ★ lmb_bra... | 2.10.b |
| + ilmb_cntlr | | ★ lmb_bra... | 2.10.b |
| + DDR_SDRAM | | ★ mpmc | 6.02.a |
| + mdm_0 | | ★ mdm | 2.00.a |
| + xps_intc_0 | | ★ xps_intc | 2.01.a |
| + Generic_Ethernet_10_100 | | ★ xps_eth... | 4.00.a |
| + DIP_Switches | | ★ xps_gpio | 2.00.a |
| + LEDS | | ★ xps_gpio | 2.00.a |
| + xps_timer_0 | | ★ xps_timer | 1.02.a |
| + RS232 | | ★ xps_uart... | 1.01.a |
| clock_generator_0 | | ★ clock_ge... | 4.01.a |
| proc_sys_reset_0 | | ★ proc_sys... | 3.00.a |



- Microblaze configuration

The screenshot shows the 'MicroBlaze Configuration Wizard' window. The title bar reads 'XPS Core Config - microblaze_0 - microblaze_v8_00_b'. The main window has a header with the 'MicroBlaze' logo and the title 'Configuration Wizard'. On the left, a sidebar titled 'Select configuration:' lists several options: 'Current Settings' (selected), 'Minimum Area', 'Maximum Performance', 'Maximum Frequency', 'Linux with MMU', 'Low-end Linux with MMU', and 'Typical'. The main area is titled 'Welcome to MicroBlaze Configuration Wizard' and contains two bullet points: 'Select a predefined configuration in the list to the left. Information about the selected configuration is shown below. Each predefined configuration completely changes the MicroBlaze parameters.' and 'To modify the configuration, click on the Next button, click on Advanced to directly access parameters in a tabbed interface, or click on OK to accept the configuration and close the dialog.' Below this, there are several checkboxes: 'Select implementation to optimize area (with lower instruction throughput)' (unchecked), 'Enable Debug' (checked), 'Use Instruction and Data Caches' (checked), 'Enable Exceptions' (unchecked), and 'Use Memory Management' (checked). A red circle highlights the 'Use Memory Management' checkbox. A yellow tooltip box points to this checkbox with the text: 'Enable Memory Management if planning to use an operating system - such as Linux - with support for virtual memory or memory protection. Note that when area optimized MicroBlaze is enabled, the Memory Management Unit is not available.' At the bottom left, there are three progress bars for 'Frequency', 'Area', and 'Performance'. At the bottom right, there are 'Next >' and 'Advanced' buttons, and two numeric input fields labeled 'BRAM' and 'MULT18'.

- Microblaze configuration

XPS Core Config - microblaze_0 - microblaze_v8_00_b

Page 2 of 6 - Performance and Instructions


Optimization


- Enable Branch Target Cache
- Branch Target Cache Size: DEFAULT


Instructions


- Enable Barrel Shifter
- Enable Floating Point Unit: NONE
- Enable Integer Multiplier: MUL32
- Enable Integer Divider
- Enable Additional Machine Status Register Instructions
- Enable Pattern Comparator


Advanced < Back Next >

Frequency 

Area 

Performance 

BRAM 

MULT18 

- Microblaze configuration

XPS Core Config - microblaze_0 - microblaze_v8_00_b

Page 4 of 6 - Caches

Instruction Cache Feature

- Size of the Instruction Cache in Bytes: 256B
- Instruction Cache Line Length: 4 words
- Instruction Cache Base Address: 0xc0000000
- Instruction Cache High Address: 0xc3ffffff
- Use Cache Links for All I-Cache Memory Accesses:
- Number of I-Cache Streams: 0
- Number of I-Cache Victims: 0

Data Cache Feature

- Size of the Data Cache in Bytes: 256B
- Data Cache Line Length: 4 words
- Data Cache Base Address: 0xc0000000
- Data Cache High Address: 0xc3ffffff
- Use Cache Links for All D-Cache Memory Accesses:
- Enable Write-back Storage Policy:
- Number of D-Cache Victims: 0

Advanced

< Back Next >

Frequency: [Progress Bar]

Area: [Progress Bar]

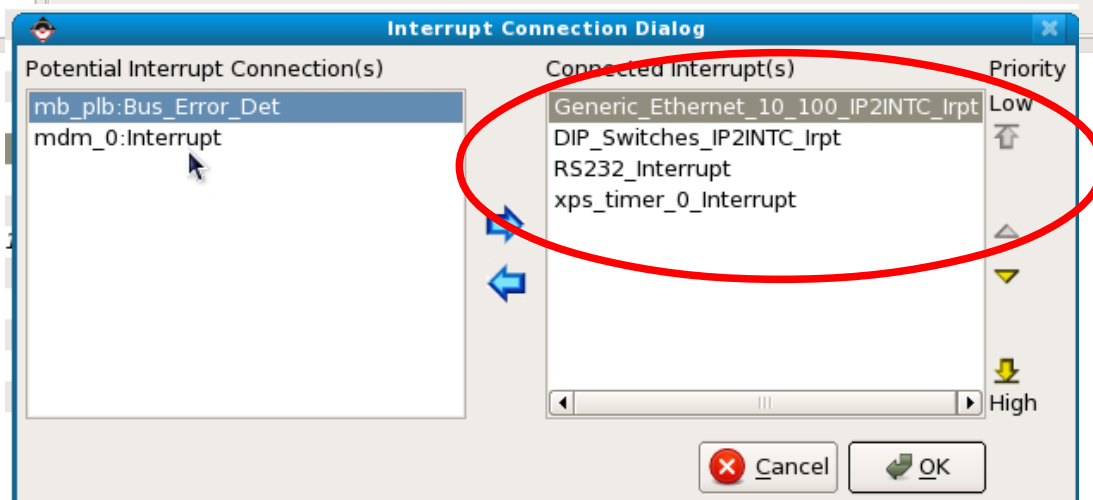
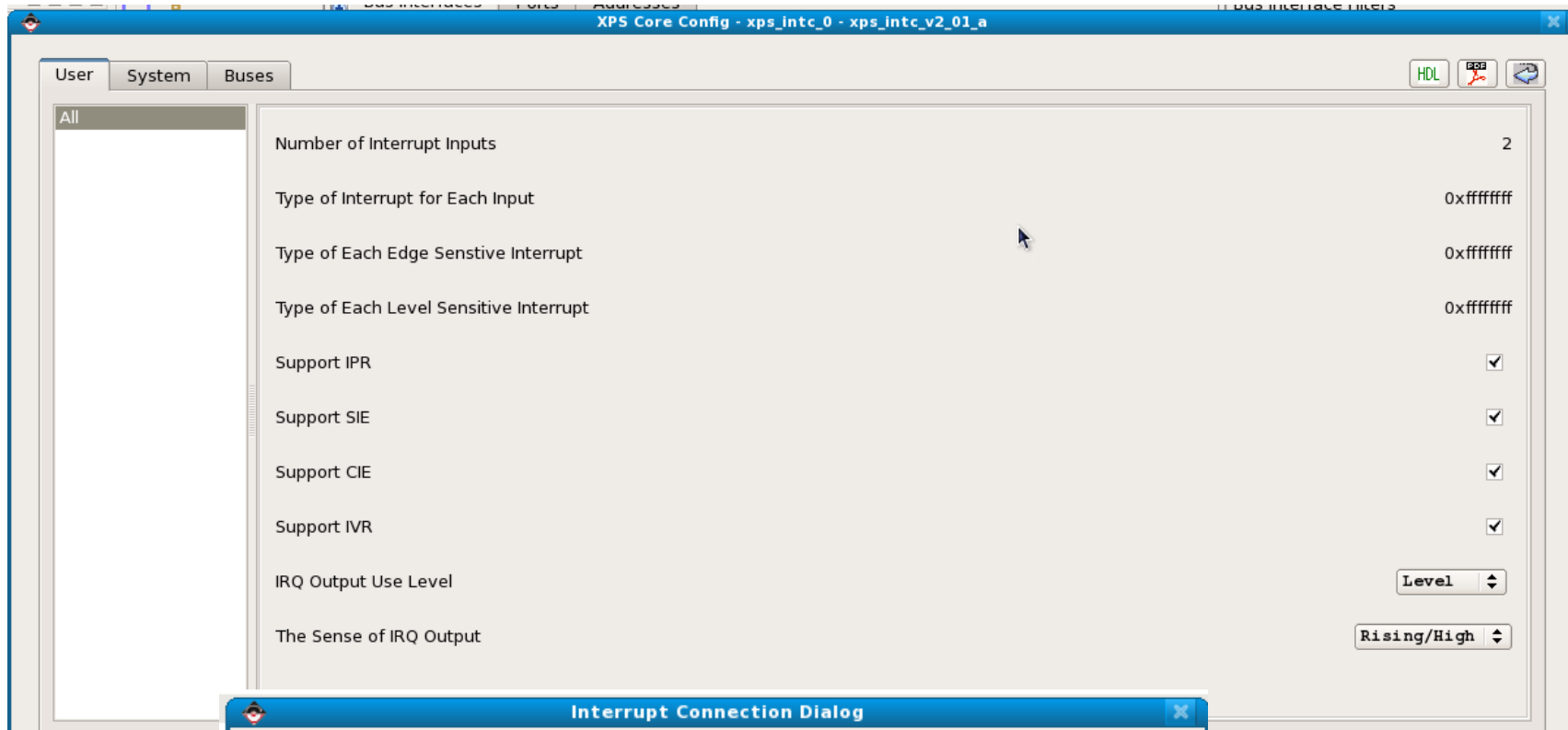
Performance: [Progress Bar]

BRAM: [Progress Bar]

MULT18: [Progress Bar]

- Microblaze configuration

The screenshot shows the 'XPS Core Config - microblaze_0 - microblaze_v8_00_b' window. The main content area is titled 'Page 5 of 6 - Memory Management Unit'. It contains several configuration options: 'Memory Management' (set to VIRTUAL), 'Data Shadow Translation Look Aside Buffer Size' (set to 4), 'Instruction Shadow Translation Look Aside Buffer Size' (set to 2), 'Enable Access to Memory Management Registers' (set to FULL), and 'Number of Memory Protection Zones' (set to 2). These five options are circled in red. At the bottom of the main area are buttons for '< Back' and 'Next >'. Below this is a summary section with 'Frequency', 'Area', and 'Performance' metrics shown as blue hatched bars. To the right of these bars are 'BRAM' and 'MULT18' resource usage indicators.



- Timer

XPS Core Config - xps_timer_0 - xps_timer_v1_02_a

User System Buses

All

The Width of Counter in Timer 32

Only One Timer is present

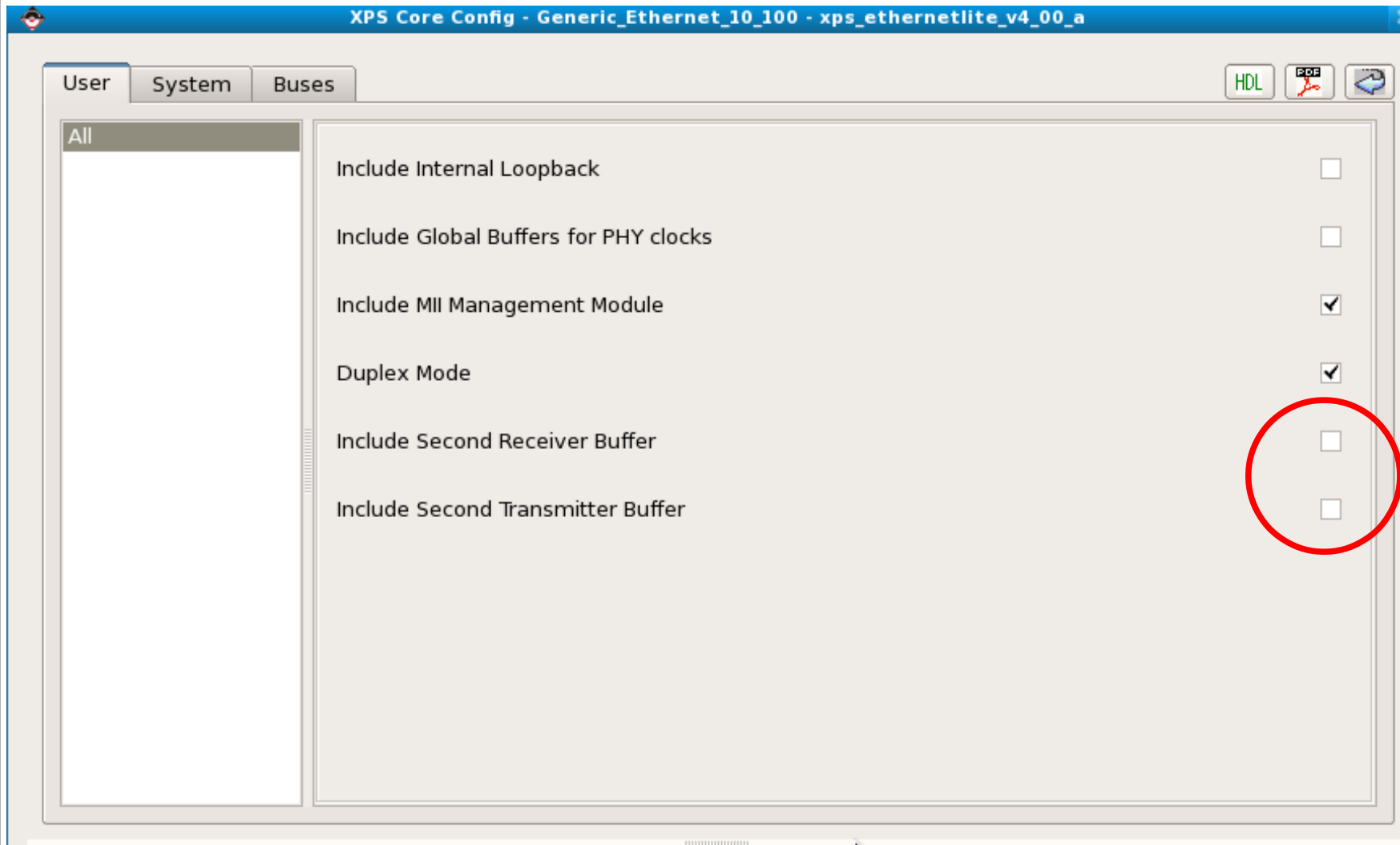
TRIG0 Active Level 1

TRIG1 Active Level 1

GEN0 Active Level 1

GEN1 Active Level 1

- Network



- Memory (MPMC)

XPS Core Config - DDR_SDRAM - mpmc_v6_02_a

Base Configuration | **Memory Interface** | Port Configuration | Advanced

Port Type Configuration

MPMC Module Interface

PORT0 | PORT1 | PORT2 | PORT3 | PORT4 | PORT5 | PORT6 | PORT7

XCL | INACTIVE | INACTIVE | INACTIVE | INACTIVE | INACTIVE | INACTIVE | INACTIVE

Common Addresses

Base Address: 0xC0000000 (SDMA Register Base Address) | 0xFFFFFFFF

LeftJustify

- Memory (MPMC)

XPS Core Config - DDR_SDRAM - mpmc_v6_02_a

Base Configuration | **Memory Interface** | Port Configuration | Advanced

Memory Part Selector

Type: **DDR** Manufacturer: * Style: * Density: * Width: * Part No.: **Select a part (209)**

Selected Memory Info

| | | | | | | | | | |
|----------|---------------------|------|------|------|-----|--------------|------------|--------------|------------|
| Part No. | MT46V32M16-6 | Size | 64MB | Type | DDR | Base Address | 0xC0000000 | High Address | 0xC3FFFFFF |
|----------|---------------------|------|------|------|-----|--------------|------------|--------------|------------|

Memory/DIMM Settings | **Memory Part Settings** | MIG Settings | MCB

Settings

Number of DIMMs: **1** Dynamic Write ODT Setting: **OFF**

Memory Data Width: **16** Partial Array Self Refresh: **FULL**

ODT Setting: **Disabled/Disable** Auto Self Refresh: **ENABLED**

Enable DQSN in DDR2: High Temp Self Refresh: **NORMAL**

Reduced Drive Output: **FULL** Memory Clock Period (ps): **10,000**

Enable Write Leveling:

Configuration

CE Width: **1**

ODT Width: **1**

Clock Width: **1**

CSn Width: **1**

No. of Ranks: **1**

Registered Memory:

Info

Memory DM Width: **2**

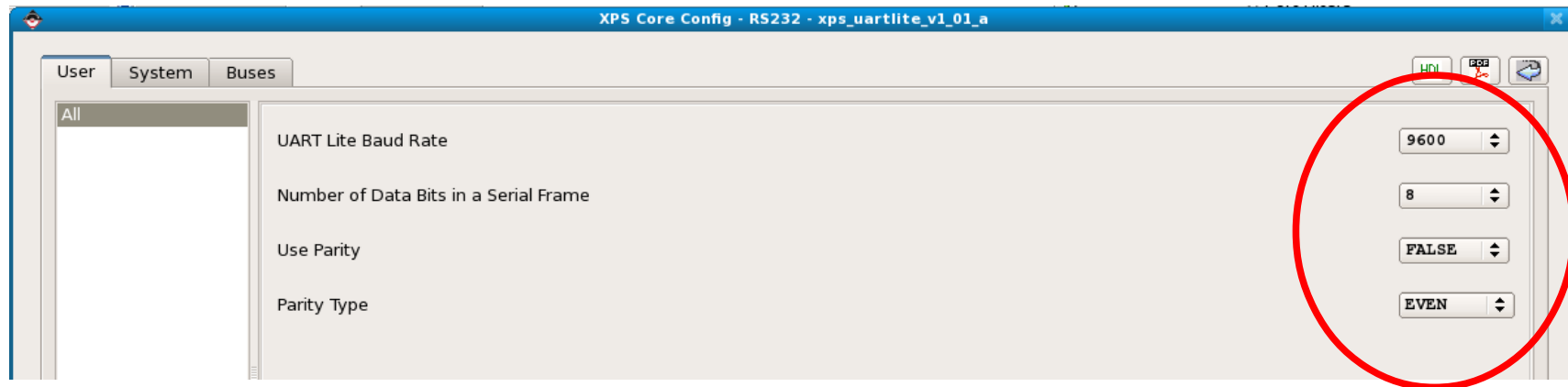
Memory Address Width: **13**

Memory Bank Address Width: **2**

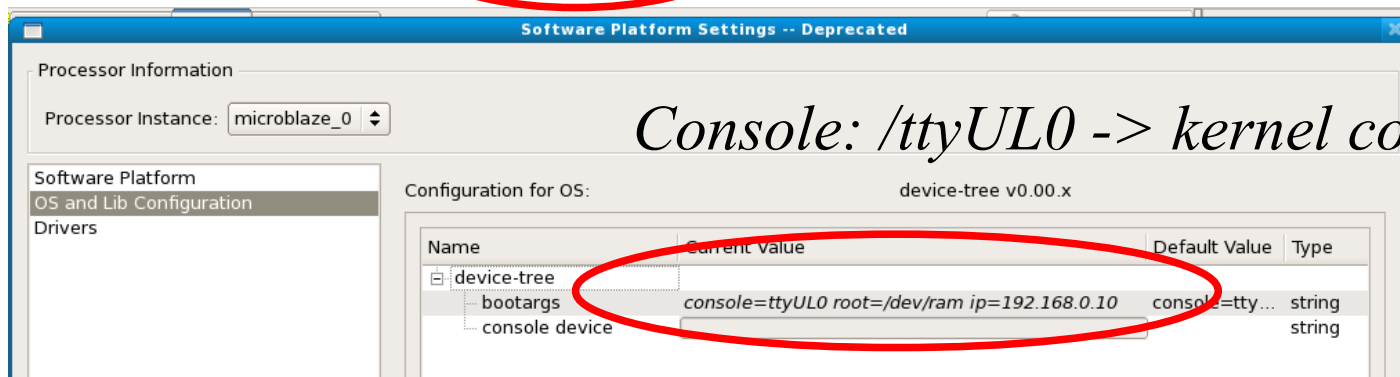
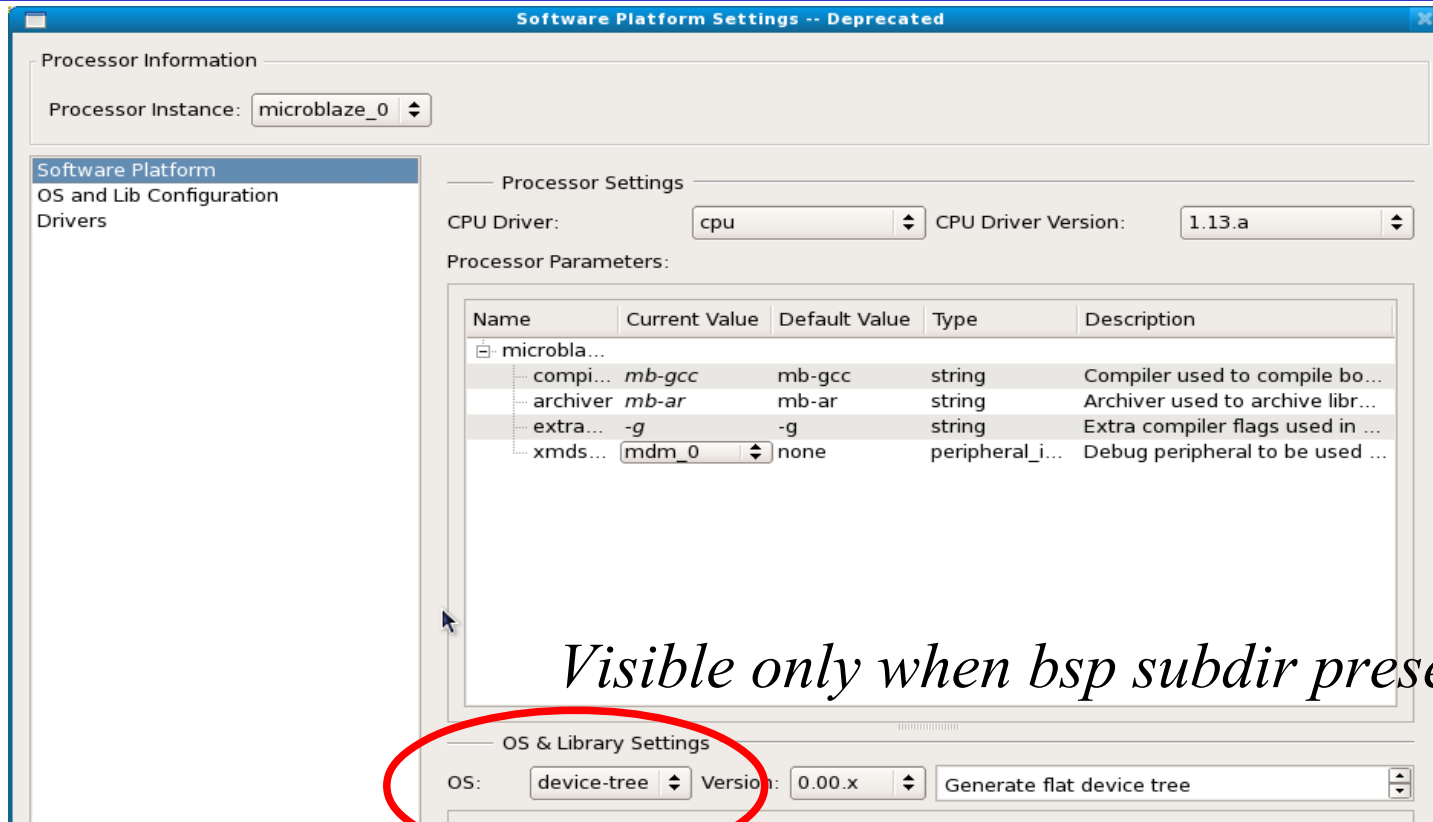
Memory DQS Width: **2**

CAS Write Latency: **5**

- Device tree generator



- Device tree generator



- HW implementation result

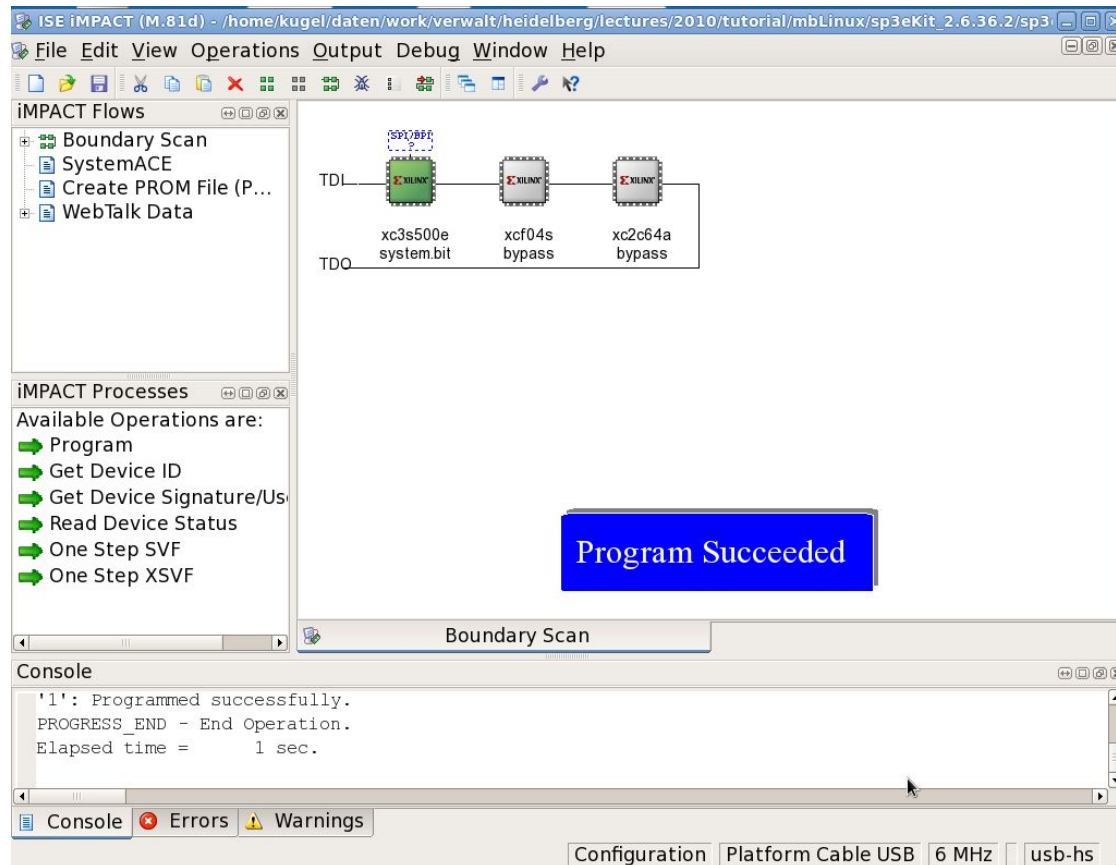
Design Summary Report (XC3S500e):

| | | |
|----------------------------------|------------------|------|
| Number of External IOBs | 79 out of 232 | 34% |
| Number of External Input IOBs | 19 | |
| Number of External Input IBUFs | 19 | |
| Number of External Output IOBs | 40 | |
| Number of External Output DIFFMs | 1 | |
| Number of External Output DIFFSs | 1 | |
| Number of External Output IOBs | 38 | |
| Number of External Bidir IOBs | 20 | |
| Number of External Bidir IOBs | 20 | |
| Number of BSCANs | 1 out of 1 | 100% |
| Number of BUFGMUXs | 5 out of 24 | 20% |
| Number of DCMs | 2 out of 4 | 50% |
| Number of MULT18X18SI0s | 3 out of 20 | 15% |
| Number of RAMB16s | 10 out of 20 | 50% |
| Number of Slices | 4612 out of 4656 | 99% |
| Number of SLICEMs | 777 out of 2328 | 33% |

○ No space left in device

Download to Starterkit (FPGA config)

- Download FPGA configuration
- Sonnect JTAG cable
- Start Impact
- Select .bit file for FPGA, no SPI, other devices in BYPASS



Download to Starterkit (XMD connect)

Download kernel via XMD

```
[kugel@pcakulap sp3eKit_2.6.36.2]$ xmd
Xilinx Microprocessor Debugger (XMD) Engine
Xilinx EDK 12.4 Build EDK_MS4.81d
XMD%
XMD% connect mb mdm
JTAG chain configuration
```

| Device | ID Code | IR Length | Part Name |
|--------|----------|-----------|-----------------|
| 1 | 41c22093 | 6 | XC3S500E |
| 2 | f5046093 | 8 | XCF04S |
| 3 | 06e5e093 | 8 | XC2C64A |

FPGA Type

CPU Config

```
MicroBlaze Processor Configuration :
-----
Version.....8.00.b
Optimization.....Performance
Interconnect.....PLB_v46
MMU Type.....Full_MMU
No of PC Breakpoints.....1
No of Read Addr/Data Watchpoints...0
No of Write Addr/Data Watchpoints..0
Instruction Cache Support.....on
Instruction Cache Base Address.....0xc0000000
Instruction Cache High Address.....0xc3ffffff
Data Cache Support.....on
Data Cache Base Address.....0xc0000000
Data Cache High Address.....0xc3ffffff
Exceptions Support.....on
FPU Support.....off
Hard Divider Support.....off
Hard Multiplier Support.....on - (Mul32)
Barrel Shifter Support.....on
MSR clr/set Instruction Support...on
Compare Instruction Support.....on
Data Cache Write-back Support.....off
Connected to "mb" target. id = 0
Starting GDB server for "mb" target (id = 0) at
TCP port no 1234
```

Download to Starterkit (Linux boot)

```
XMD% dow ./simpleImage.xilinx_sp3
```

```
Downloading Program -- ./simpleImage.xilinx_sp3
```

```
section, .text: 0xc0000000-0xc027cadf
section, .init.text: 0xc0346000-0xc035e1e3
section, .init.ivt: 0xc035fe50-0xc035fe77
section, __fdt_blob: 0xc027cae0-0xc0280adf
section, .rodata: 0xc0281000-0xc031892f
section, __ksymtab: 0xc0318930-0xc031ceff
section, __ksymtab_gpl: 0xc031cf00-0xc031efff
section, __ksymtab_strings: 0xc031f000-0xc032cdf7
section, __param: 0xc032cdf8-0xc032dfff
section, __ex_table: 0xc032e000-0xc032ecd7
section, .sdata2: 0xc032ecd8-0xc032efff
section, .data: 0xc032f000-0xc03442df
section, .data..shared_aligned: 0xc03442e0-0xc034436b
section, .init.data: 0xc035e1e4-0xc035fe4f
section, .init.setup: 0xc035fe78-0xc03600e7
section, .initcall.init: 0xc03600e8-0xc036032b
section, .con_initcall.init: 0xc036032c-0xc036032f
section, .init.ramfs: 0xc0361000-0xc04ef45f
section, .bss: 0xc04f0000-0xc051cf07
```

```
Setting PC with Program Start Address 0xc0000000
```

```
System Reset .... DONE
```

```
XMD% con
```

```
Processor started. Type "stop" to stop processor
```


Linux boot console output

Ramdisk addr 0x00000003, Compiled-in FDT at 0xc027cae0

Linux version 2.6.36.2 (kugel@pcakulap) (gcc version 4.1.2 20070214 (Xilinx 12.3 Build EDK_MS3.66
14 Jul 2010)) #43 PREEMPT Sat Jan 8 19:28:40 CET 2011

...

setup_memory: max_mapnr: 0x4000

setup_memory: min_low_pfn: 0xc0000

setup_memory: max_low_pfn: 0xc4000

On node 0 totalpages: 16384

...

Kernel command line: console=ttyUL0 root=/dev/ram ip=192.168.0.10

...

Memory 59664k/65536k available

xlnx,xps-intc-1.00.a #0 at 0xc4000000, num_irq=4, edge=0xb

xlnx,xps-timer-1.00.a #0 at 0xc4004000, irq=0

Calibrating delay loop... 23.75 BogoMIPS (lpj=118784)

XGpio: /plb@/gpio@81420000: registered

XGpio: /plb@/gpio@81400000: registered

...

io scheduler cfq registered (default)

84000000.serial: ttyUL0 at MMIO 0x84000000 (irq = 1) is a uartlite

console [ttyUL0] enabled

...

++ Starting INETD (e.g. for ftp)

Sun Jan 9 19:15:09 2011

rcS Complete

/ #

2011-05-05

Login prompt

FPGA-CC, A. Kugel, MB Linux

Running Linux on Starterkit

- **Access**
- **Commands**
- **Development**
 - ⇒ **WWW**
 - ⇒ **Applications**
 - ⇒ **Modules**

○ Console and telnet

⇒ **Serial port is primary Linux terminal**

⇒ **With Microblaze serial port can be run over JTAG (not tested)**

⇒ **Several telnet terminals (default: 5) available**

- `[kugel@akudesk linux-2.6.36.2]$ telnet 192.168.0.10`

- `Trying 192.168.0.10...`

- `Connected to 192.168.0.10.`

- `Escape character is '^]'.`

- `/ # uname -a`

- `Linux sp3eStartKit 2.6.36.2 #43 PREEMPT Sat Jan 8 19:28:40 CET 2011
microblaze GNU/Linux`

- `/ #`

⇒ **Per default root access without password**

⇒ **Additional users can be added via adduser**

- Access (2)

○ Ftp

⇒ **FTP daemon started via inetd**

⇒ **Configuration in /etc/inetd/inetd.conf**

- **/ # cat /etc/inetd/inetd.conf**
- **21 stream tcp nowait ftp ftpd ftpd -w /tmp**
 - **Default user ftp, created by startup script in /etc/init.d/rcS**
 - **Default transfer directory /tmp**

⇒ **Cross-compiled binaries (and other files) can be uploaded via ftp**

⇒ **Tar and gzip work as usual to simplify uploads**

- Linux commands

○ Basic tools

⇒ ls, cp, mv, mkdir, chmod, find, date, ...

○ System tools

⇒ Dmesg, ps, kill, ifconfig, udhcpc, ...

○ System files

⇒ /dev

- Device nodes

⇒ /etc

- Scripts, configuration files

⇒ /proc, e.g.

- /proc/cpuinfo
- /proc/interrupts

⇒ /sys/class, e.g.

- /sys/class/gpio

```
> cat /proc/cpuinfo
CPU-Family:      MicroBlaze
FPGA-Arch:      virtex5
CPU-Ver:        Unknown
CPU-MHz:        50.00
BogoMips:       23.75
HW:
Shift:          yes
MSR:            yes
PCMP:           yes
DIV:            no
MMU:            3
MUL:            v1
FPU:            no
Exc:
Icache:         0kB      line length:   16B
Dcache:         0kB      line length:   16B
write-through
HW-Debug:       yes
PVR-USR1:       00
PVR-USR2:       00000000
Page size:      4096
/ # cat /proc/interrupts
CPU0
0:    2960701      edge Xilinx INTC timer
1:      120        edge Xilinx INTC uarllite
3:     4191        edge Xilinx INTC eth0
/ # █
```

- Development cycle (user land)

○ Host based

⇒ Linux gcc, g++ cross-compilers

- `mb-linux-gcc/g++` (alias `microblaze-unknown-linux-gnu-gcc/g++`)
- E.g. `mb-linux-gcc -g -O0 -L mbtooldir/microblaze_v1.0/microblaze-unknown-linux-gnu/microblaze-unknown-linux-gnu/sys-root/usr/lib --sysroot=linuxdir -isystem mbtooldir/microblaze_v1.0/microblaze-unknown-linux-gnu/microblaze-unknown-linux-gnu/sys-root/usr/include -o hello hello.c -static -lc`

⇒ Limited functionality due to static linking and fewer libs

- Potentially can be improved by cross-compiling full GLIBC

⇒ Debugging on host

- Linux GDB and GDBSERVER not (yet) operational on Microblaze target
- EDK gdb not suitable for Linux applications

⇒ Advantage: identical code on host and target in many cases

○ Transfer via ftp

○ Serious error messages potentially go to system log

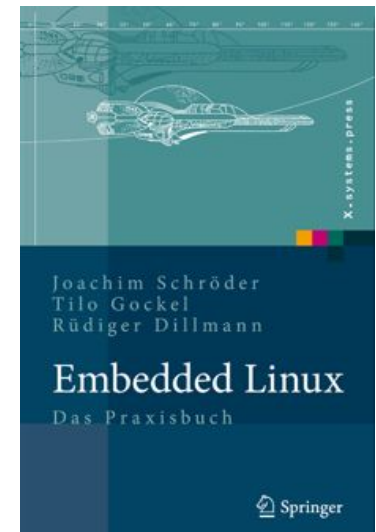
○ On crash: kill process from other terminal

- Development cycle (kernel)

- **Linux: User land (regular applications) vs. Kernel (drivers/modules)**
 - ⇒ **Static (boot time loaded) drivers**
 - For ES: UART, timer, network, IRQ
 - Disk, VGA not relevant
 - ⇒ **Loadable kernel modules**
 - insmod
 - rmmod
 - Lsmod
 - Big advantage: no need to recompile kernel
- **Same host based development, but different includes and libs**
 - ⇒ **Limited debugging on host**
 - ⇒ **Debugging via printk() and kernel log**

Applications

- **Simple applications (... hello world ...)**
- **Simple Timing**
- **Simple HW access via GPIO**
- **Advanced apps (mostly from Embedded Linux book)**
 - ⇒ **Threads, Mutexes**
 - ⇒ **Sockets**
 - ⇒ **Periodic threads**
 - ⇒ **IPC**

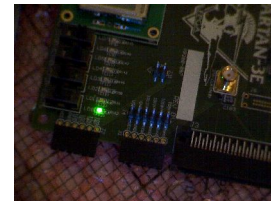


Many useful code samples at

<http://www.praxisbuch.net/embedded-linux/downloads/embedded-linux-source-1.0.zip>

- Simple applications

- Simple „hello world“-type applications straightforward
 - ⇒ Just different compiler, include and lib directories
- Simple timing
 - ⇒ Standard Linux interval timer
 - Install signal handler: `signal(SIGALRM, sigHandler);`
 - Set time: `setitimer(timer, &tval, 0);`
 - Wait for signal: `sigwait(&sigList, &theSig);`
 - ⇒ Runs on both host and target
- HW access, e.g. to LEDs and switches
 - ⇒ **User apps cannot directly access physical memory**
 - ⇒ **GPIO via sysfs**
 - GPIOs are available via `/sys/class/gpio`
 - Use from shell (script) via `echo` and `cat`
 - Use from program via `fread/fwrite` to sysfs files
 - Very simple, slow
 - ⇒ **GPIO via mmap**
 - Map physical memory via `/dev/mem` file to virtual address
 - Much faster, only for programs



Hardware access via /dev/mem

Example mbFastIo

```
// open memory access
memfd = open("/dev/mem", O_RDWR | O_SYNC);

// Map physical device memory (1 page) into user space
mapped_base = mmap(0, MAP_SIZE, PROT_READ | PROT_WRITE, MAP_SHARED,
memfd, dev_base & ~MAP_MASK);

// get the address of the device in user space (offset from base address)
mapped_dev_base = mapped_base + (dev_base & MAP_MASK);

// write to the direction register so all the GPIOs are on output to drive LEDs
*((unsigned long *) (mapped_dev_base + GPIO_DIRECTION_OFFSET)) = 0;

// set output value
*((unsigned long *) (mapped_dev_base + GPIO_DATA_OFFSET)) = 0x1234;

// unmap and close
munmap(mapped_base, MAP_SIZE);
close(memfd);
```

- Advanced applications

○ Multi-threading

⇒ **Single program, multiple threads**

⇒ **Threads share address space**

- **Data exchange via global variables (structures) possible**
- **Issue: synchronisation and resource sharing**

⇒ **Posix thread, mutex, semaphore, condition variables**

- **pthread_create(...);**
- **pthread_join(...);**
- **pthread_mutex_lock(&mutex);**
- **pthread_cond_signal(&cond);**
- **pthread_mutex_unlock(&mutex);**

```
$ ./threads_basic0
./threads_basic0: condition demo
  Thread 1: reading value
  Thread 2: incrementing value
Exit Program with Ctrl+C
Initial value is 4
(2) Incrementing value, is now 5
(1) Read value 5
(2) Incrementing value, is now 6
(1) Read value 6
```

```
$ ftp 192.168.0.10
ftp> put threads_basic1
226 Operation successful
683159 bytes sent in 3,05 secs
(223,94 Kbytes/sec)
ftp> quit
```

```
$ telnet 192.168.0.10
Trying 192.168.0.10...
Connected to 192.168.0.10.
/ # chmod +x /tmp/threads_basic1
/ # /tmp/threads_basic1
/tmp/threads_basic1: condition demo
  Thread 1: reading value
  Thread 2: incrementing value
Exit Program with Ctrl+C
Initial value is 4
(2) Incrementing value, is now 5
(1) Read value 5
(2) Incrementing value, is now 6
(1) Read value 6
```

- Advanced applications (3)

○ Performance

⇒ Embedded Linux book „Servo“ example

- Periodic thread, 20 ms, 1.6GHz ATOM
- Kernel 2.6, RT prio: max 297 μ s deviation

⇒ MB on Spartan3: max +/-7ms deviation

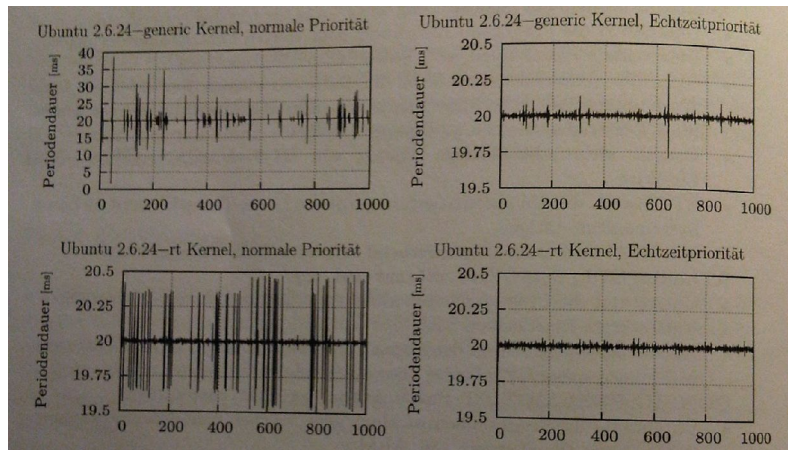
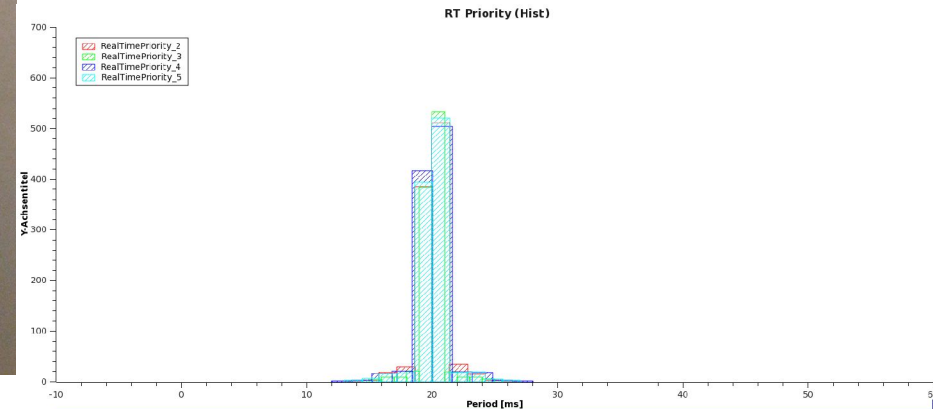
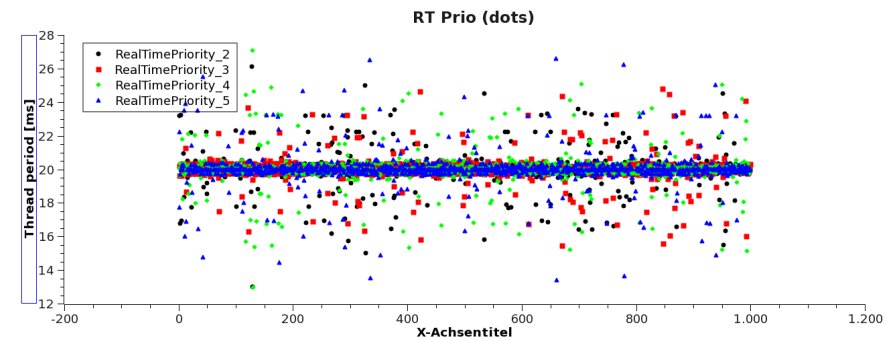


Abb. 12.7. Grafische Darstellung der Periodendauer von 1000 aufeinanderfolgenden Ausführungen des ServoThreads für die vier untersuchten Konfigurationen.

| Konfiguration | Min | Avg | Max |
|-------------------------------------------------|--------------|---------------|------------------|
| Ubuntu 2.6.24-generic Kernel, normale Priorität | 0,01 μ s | 24,71 μ s | 18695,85 μ s |
| Ubuntu 2.6.24-generic Kernel, Echtzeitpriorität | 0,01 μ s | 9,35 μ s | 297,90 μ s |
| Ubuntu 2.6.24-rt Kernel, normale Priorität | 0,0 μ s | 6,56 μ s | 484,37 μ s |
| Ubuntu 2.6.24-rt Kernel, Echtzeitpriorität | 0,01 μ s | 6,78 μ s | 116,88 μ s |

Tabelle 12.2. Die minimale (Min), durchschnittliche (Avg) und maximale (Max) Abweichung von der Periode für die vier untersuchten Konfigurationen bei jeweils 1000 aufeinanderfolgenden Ausführungen.



- Advanced applications (4)

○ Network programming

- ⇒ Simple UDP sockets (unreliable)
- ⇒ Standard TCP sockets
- ⇒ Client-server applications
- ⇒ Remote display (QT, ...)

○ Watch endiannes

- ⇒ Use htonl, htons, ntohs, ntohl
- ⇒ Carefull with structs containing non-aligned members
 - Strings, short, ...

○ Check firewall

```
$ ./receiver0 8095
Receiving UDP-packets at port 8095..
Received string: sdasdk from
192.168.0.10:46414
Received string: 123456 from
192.168.0.10:46414
Received string: sdqd from
192.168.0.10:46414
^C
$
```

```
# sender1 192.168.0.134 8095
Sending UDP-packets to
192.168.0.134:8095..
Enter your string now, ENTER to send
sdasdk
Enter your string now, ENTER to send
123456
Enter your string now, ENTER to send
sdqd
Enter your string now, ENTER to send
^C
/ #
```

- Kernel modules

- **Device classes: character vs. block**
 - ⇒ **Simple load/unload via insmod, rmmod**
 - **Module version must match kernel version**
 - **Modules to be placed in /lib/modules/<kernel-version>/**
 - ⇒ **Modules can access physical memory**
 - ⇒ **Modules cannot use user-land libraries and files**
 - ⇒ **Modules can interact to user-land via /proc filesystem**
- **Samples from „Embedded Linux“ book**
 - ⇒ **Module template**
 - **init, exit**
 - **open, close, read, write**
 - **ioctl (device control)**
 - **Minimal module < 20 lines of code (no real function)**
 - ⇒ **Kernel - Userspace transfers**
 - **E.g. character device**
- **UIO**
 - ⇒ **User space IO/ drivers: exists, but not information**

Webserver

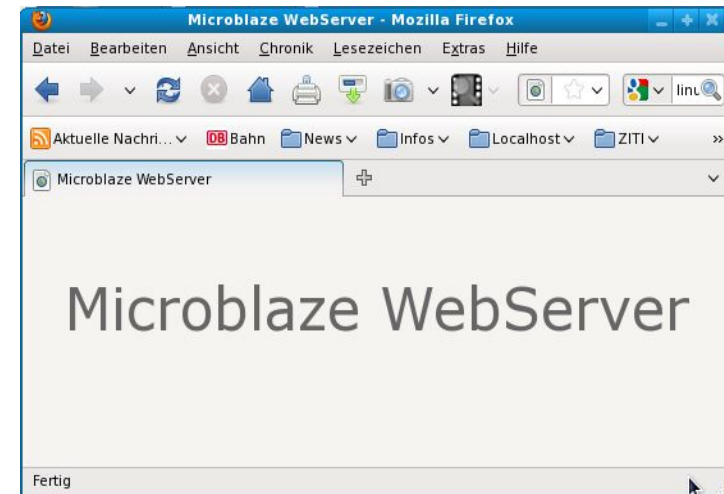
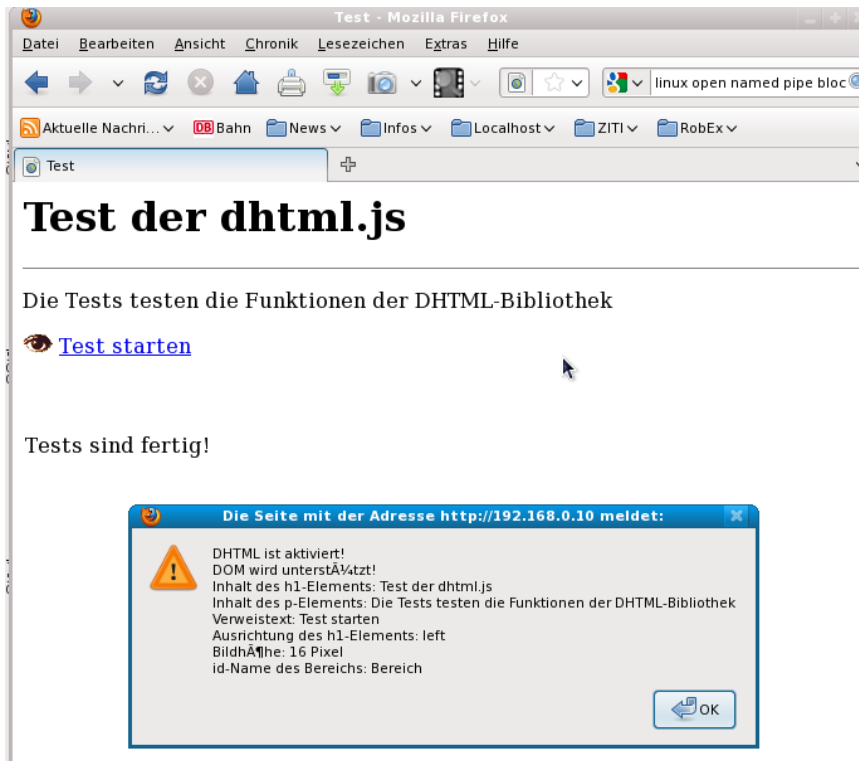
○ Busybox comes with httpd daemon (web server)

⇒ Simple configuration: start in /etc/init.d/rcS

- /sbin/httpd -h /var/www

⇒ Plain html and DHTML

- Simple display
- Downloads (e.g. log files)
- Interactions via Javascript



- Advanced WWW

○ CGI

- ⇒ Access to scripts and programs on server
- ⇒ Full access possible (e.g. measurements, control)



click on a button to see the output of this command



A screenshot of the Mozilla Firefox browser window showing the output of the 'ps' command. The output is a table with columns for PID, USER, TIME, and COMMAND. The browser's address bar shows `http://192.168.0.10/cgi-bin/ps`.

| PID | USER | TIME | COMMAND |
|-----|------|------|--------------------------------------|
| 1 | 0 | 0:24 | init |
| 2 | 0 | 0:00 | [kthreadd] |
| 3 | 0 | 0:00 | [ksoftirqd/0] |
| 5 | 0 | 0:00 | [kworker/u:0] |
| 6 | 0 | 0:00 | [khelper] |
| 7 | 0 | 0:01 | [sync_supers] |
| 8 | 0 | 0:00 | [bdi-default] |
| 9 | 0 | 0:00 | [kblockd] |
| 10 | 0 | 0:00 | [kmmcd] |
| 11 | 0 | 0:00 | [rpciod] |
| 13 | 0 | 0:00 | [khungtaskd] |
| 14 | 0 | 0:00 | [kswapd0] |
| 15 | 0 | 0:00 | [fsnotify_mark] |
| 16 | 0 | 0:00 | [aio] |
| 17 | 0 | 0:00 | [nfsiod] |
| 18 | 0 | 0:00 | [crypto] |
| 23 | 0 | 0:00 | [kworker/u:1] |
| 36 | 0 | 0:00 | /sbin/syslogd |
| 38 | 0 | 0:02 | /sbin/klogd |
| 41 | 0 | 0:16 | /sbin/telnetd -l /bin/sh |
| 47 | 0 | 0:00 | /sbin/httpd -h /var/www |
| 56 | 0 | 0:00 | /sbin/inetd -e /etc/inetd/inetd.conf |
| 60 | 0 | 0:00 | /bin/sh |
| 97 | 0 | 0:00 | [kworker/0:0] |
| 127 | 0 | 0:25 | [kworker/0:2] |
| 130 | 0 | 0:00 | /bin/sh |
| 134 | 0 | 0:01 | /bin/sh |
| 168 | 0 | 0:00 | less /etc/init.d/rcS |
| 171 | 0 | 0:00 | [kworker/0:1] |
| 178 | 0 | 0:00 | /sbin/httpd -h /var/www |
| 179 | 0 | 0:00 | /bin/sh ps |
| 180 | 0 | 0:00 | ps -ef |

- ⇒ Information transfer to and from CGI application

SAN (Storage Area Network) – host preps

Check VBLADE service on host

```
○ $ cat /etc/vblade.conf
# network_device shelf slot file/disk/partition
mac[,mac[,mac]]
#eth3 0 0 /home/kugel/temp/aoe/aoe.dat
00:0A:35:08:21:00
```

Edit proper interface, filename and MAC address

Start service

```
$ sudo service vblade restart
vblade starten:
.../aoe.dat (e0.0@wlan0) [pid 24785]
[ OK ]
```

SAN - discovery

○ / # aoe-sancheck

Probing... etherd/e0.0: unknown partition table done.

=====

INTERFACE SUMMARY

=====

| Name | Status | MTU | PCI ID |
|------|--------|------|--------|
| eth0 | UP | 1500 | |

=====

DEVICE SUMMARY

=====

| Device | Macs | Payload | Local Interfaces |
|--------|------|---------|------------------|
| e0.0 | 1 | 1024 | eth0 |

SAN – mount

○ / # **n_partitions=1 n_shelves=1 aoe-mkdevs /dev/etherd**

sh: set: -e: invalid option

sh: set: -e: invalid option

○ / # **mkdir /usr/local**

○ / # **mount /dev/etherd/e0.0 /usr/local**

EXT2-fs (etherd/e0.0): warning: mounting unchecked fs,
running e2fsck is recommended

○ / # **df**

| Filesystem | 1K-blocks | Used | Available | Use% | Mounted on |
|------------------|-----------|--------|-----------|------|------------|
| /dev/etherd/e0.0 | 1032088 | 271788 | 707872 | 28% | /usr/local |

SAN – use

○ **/ # ls /usr/local/**

| | |
|----------|------------------------------|
| bin | lost+found |
| etc | microblaze-unknown-linux-gnu |
| lib | mist.txt |
| libs.tgz | sbin |
| libsrc | usr |

○ **... use disk ...**

○ **/ # cp /usr/local/mist.txt /tmp/**

○ **/ # cat /tmp/mist.txt**

```
export HOME='/'  
export TERM='vt102'
```

...

○ **/ # umount /usr/local/**

To Do's

- **Boot loader for FLASH (replace XMD)**
- **Network fixes**
 - ⇒ **DNS resolution (nslookup not working)**
 - ⇒ **SSH (*dropbear* not compiling)**
 - ⇒ **NFS/CIFS mount (no connection yet)**
- **Tools: gcc4.6 should support Mblaze natively. Verify!**
- **Libraries**
 - ⇒ **Test Xilinx shared libs**
 - ⇒ **Port standard GLIBC**
 - ⇒ **Libs need much space in ramfs**
 - **Usefull only with network mount working**
- **Debugging**
 - ⇒ **Port gdb or gdbserver**
- **Remote graphics**
 - ⇒ **Nano-X, QT client**
- **<http://li5.ziti.uni-heidelberg.de/lectures/2010hws/embedded/>**